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Multisensor Fusion and Integration

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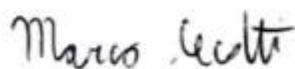


Best Paper

Calibration-free IMU-based Kinematic State Estimation for Robotic Manipulators

Michael Fennel, Lukas Driller, Antonio Zea, Uwe Hanebeck

Dr. Marco Cecotti

A handwritten signature in black ink that reads 'Marco Cecotti'.

Dr. Daniel Clarke

A handwritten signature in black ink that reads 'Dan Clarke'.

Dr. Dhiraj Gulati

A handwritten signature in black ink that reads 'Dhiraj Gulati'.

